

Chapter 10

And, Finally...

The Stack

Stacks: An Abstract Data Type

A LIFO (last-in first-out) storage structure.

- The **first** thing you put in is the **last** thing you take out.
- The **last** thing you put in is the **first** thing you take out.

This means of access is what defines a stack, not the specific implementation.

Two main operations:

PUSH: add an item to the stack

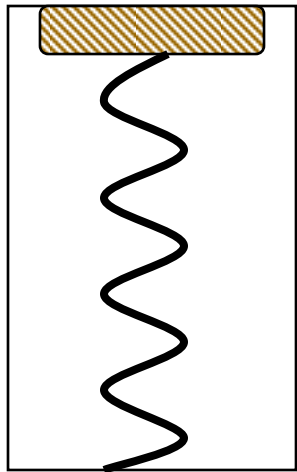
POP: remove an item from the stack



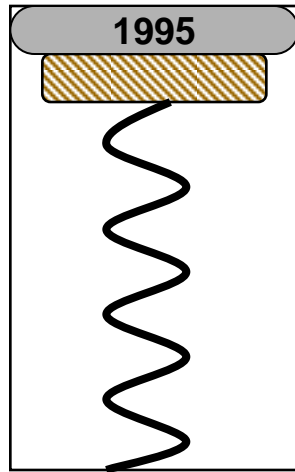
img src: edarts.net

A Physical Stack

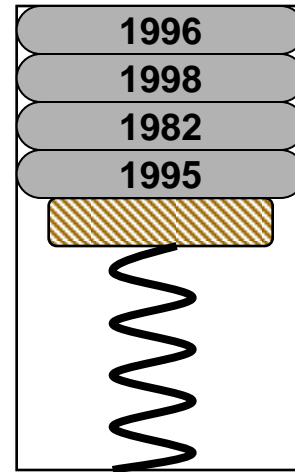
Coin rest in the arm of an automobile



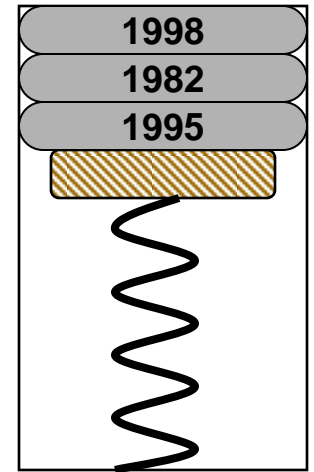
Initial State



After One Push



After Three More Pushes

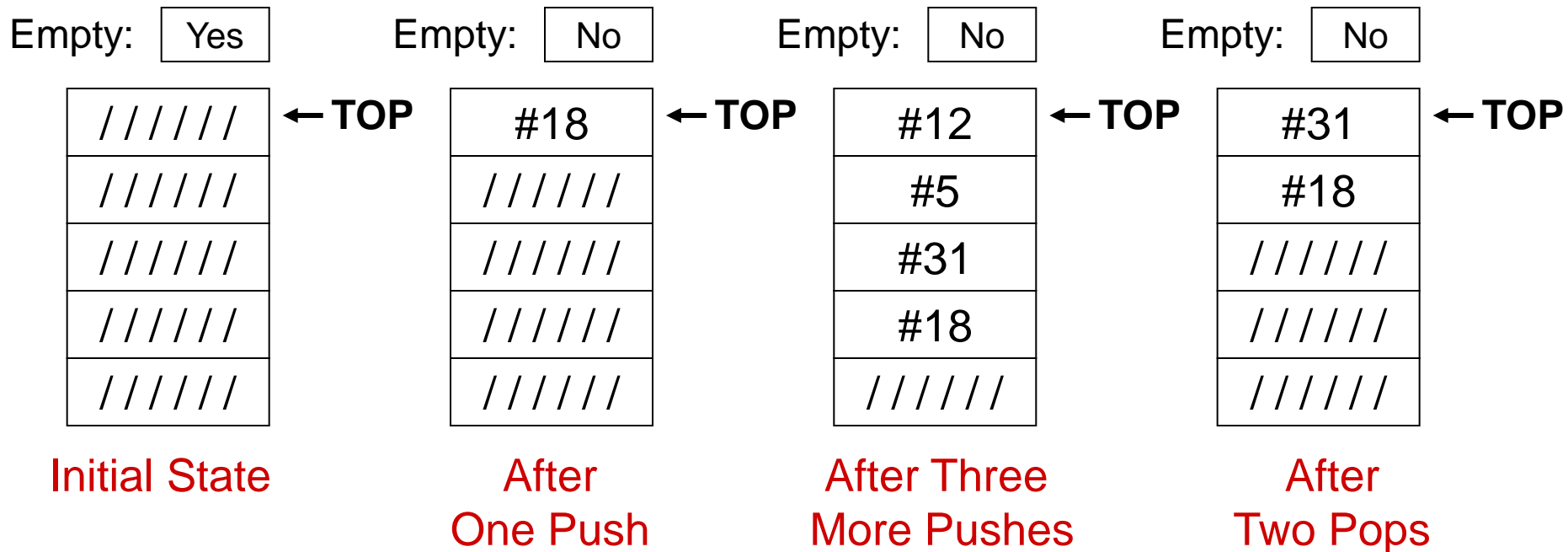


After One Pop

First quarter out is the last quarter in.

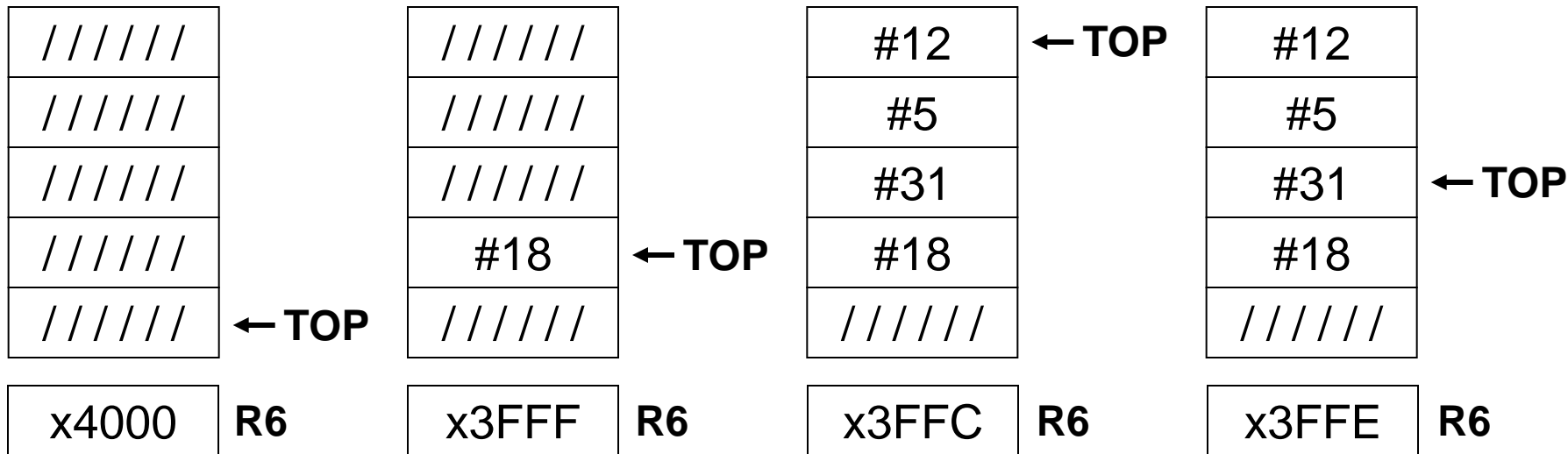
A Hardware Implementation

Data items move between registers



A Software Implementation

Data items don't move in memory,
just our idea about where the TOP of the stack is.



Initial State

After
One Push

After Three
More Pushes

After
Two Pops

By convention, R6 holds the Top of Stack (TOS) pointer.

Basic Push and Pop Code

For our implementation, stack grows downward
(when item added, TOS moves closer to 0)

Push

```
ADD    R6, R6, #-1 ; decrement stack ptr
STR    R0, R6, #0  ; store data (R0)
```

Pop

```
LDR    R0, R6, #0  ; load data from TOS
ADD    R6, R6, #1  ; increment stack ptr
```

Pop with Underflow Detection

If we try to pop too many items off the stack, an **underflow** condition occurs.

- Check for underflow by checking TOS before removing data.
- Return status code in R5 (0 for success, 1 for underflow)

```
POP    LD    R1, EMPTY    ; EMPTY = -x4000
      ADD  R2, R6, R1    ; Compare stack pointer
      BRz  FAIL          ; with xC000 (= -x4000)
      LDR  R0, R6, #0
      ADD  R6, R6, #1
      AND  R5, R5, #0    ; SUCCESS: R5 = 0
      RET
FAIL   AND  R5, R5, #0    ; FAIL: R5 = 1
      ADD  R5, R5, #1
      RET
EMPTY  .FILL xC000
```

Push with Overflow Detection

If we try to push too many items onto the stack, an **overflow** condition occurs.

- Check for overflow by checking TOS before adding data.
- Return status code in R5 (0 for success, 1 for overflow)

```
PUSH  LD   R1, MAX      ; MAX = -x3FFB
      ADD  R2, R6, R1   ; Compare stack pointer
      BRz  FAIL        ; with xC005 (= -x3FFB)
      ADD  R6, R6, #-1
      STR  R0, R6, #0
      AND  R5, R5, #0   ; SUCCESS: R5 = 0
      RET
FAIL  AND  R5, R5, #0   ; FAIL: R5 = 1
      ADD  R5, R5, #1
      RET
MAX   .FILL xC005
```


Interrupt-Driven I/O (Part 2)

Interrupts were introduced in Chapter 8.

1. External device raises an interrupt when it needs attention.
2. Processor saves state and starts service routine.
3. When finished, processor restores state and resumes program.

*Interrupt is an mysterious subroutine call,
triggered by an external event.*

Chapter 8 didn't explain how (2) and (3) occur, because it involves a **stack**.

Now, we're ready...

Processor State

What state is needed to completely capture the state of a running process?

Memory

Program Counter

- Pointer to next instruction to be executed.

General-Purpose Registers (R0~R7)

Processor Status Register

- Privilege [15], Priority Level [10:8], Condition Codes [2:0]



P = 0: Supervisor Mode

P = 1: User Mode

Miscellaneous Registers: Saved.SSP, Saved.USP (will see next), etc

Supervisor Stack

A special region of memory is used as the stack for interrupt service routines.

- **Initial Supervisor Stack Pointer (SSP) stored in Saved.SSP.**
- **Another register for storing User Stack Pointer (USP): Saved.USP.**

Want to use R6 as stack pointer.

- **So that our PUSH/POP routines still work.**

When switching from User mode to Supervisor mode (as result of interrupt), save R6 to Saved.USP.

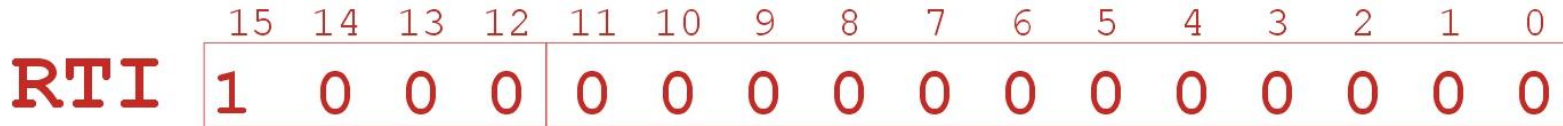
Invoking the Service Routine – The Details

1. If **Priv = 1** (user),
 Saved.USB ← R6; R6 ← Saved.SSP.
2. Push **PSR** and **PC** to **Supervisor Stack**.
3. Set **PSR[15] ← 0** (supervisor mode).
4. Set **PSR[10:8] ← priority of interrupt being serviced.**
5. Set **PSR[2:0] ← 0.**
6. Set **MAR ← x01vv**, where **vv = 8-bit interrupt vector** provided by interrupting device (e.g., keyboard = x80).
7. Load memory location (**M[x01vv]**) into **MDR**.
8. Set **PC ← MDR**; now first instruction of **ISR** will be fetched.

Note: This all happens between the **STORE RESULT** of the last user instruction and the **FETCH** of the first **ISR** instruction (i.e., atomic)

Returning from Interrupt

Special instruction – RTI – that restores state.

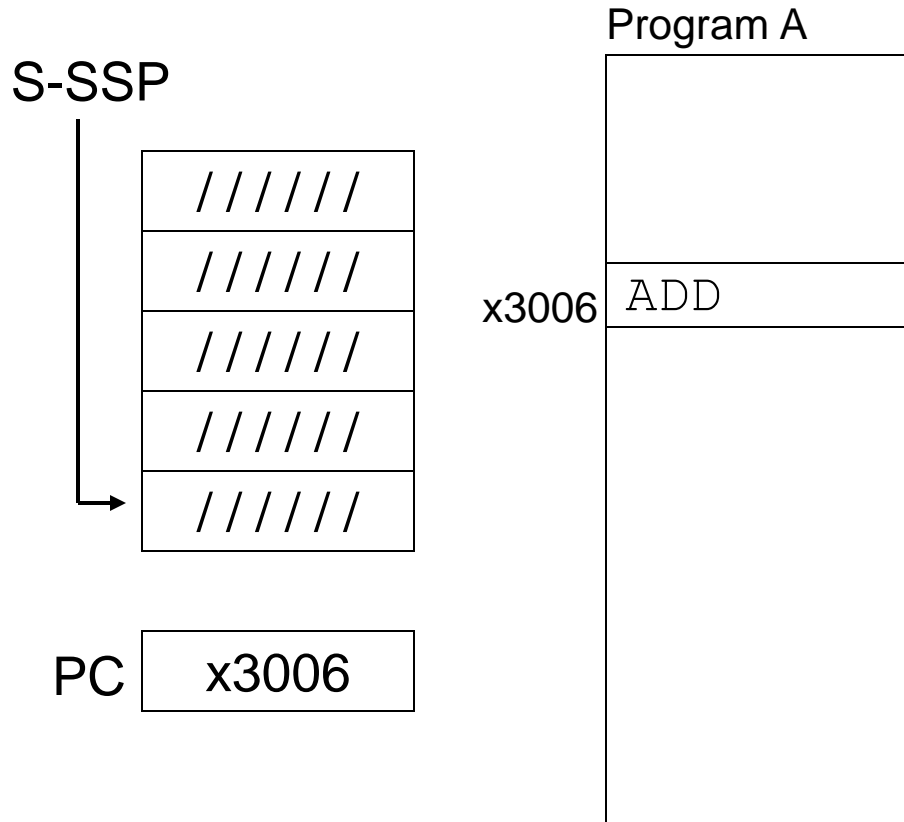


1. **Pop PC from supervisor stack.** ($PC = M[R6]$; $R6 = R6 + 1$)
2. **Pop PSR from supervisor stack.** ($PSR = M[R6]$; $R6 = R6 + 1$)
3. **If $PSR[15] = 1$** (if previous mode is USER mode), **$R6 = \text{Saved.USP}$.**
(If going back to user mode, need to restore User Stack Pointer.)

RTI is a privileged instruction.

- **Can only be executed in Supervisor Mode.**
- **If executed in User Mode, causes an exception.**
(More about that later.)

Example (1)

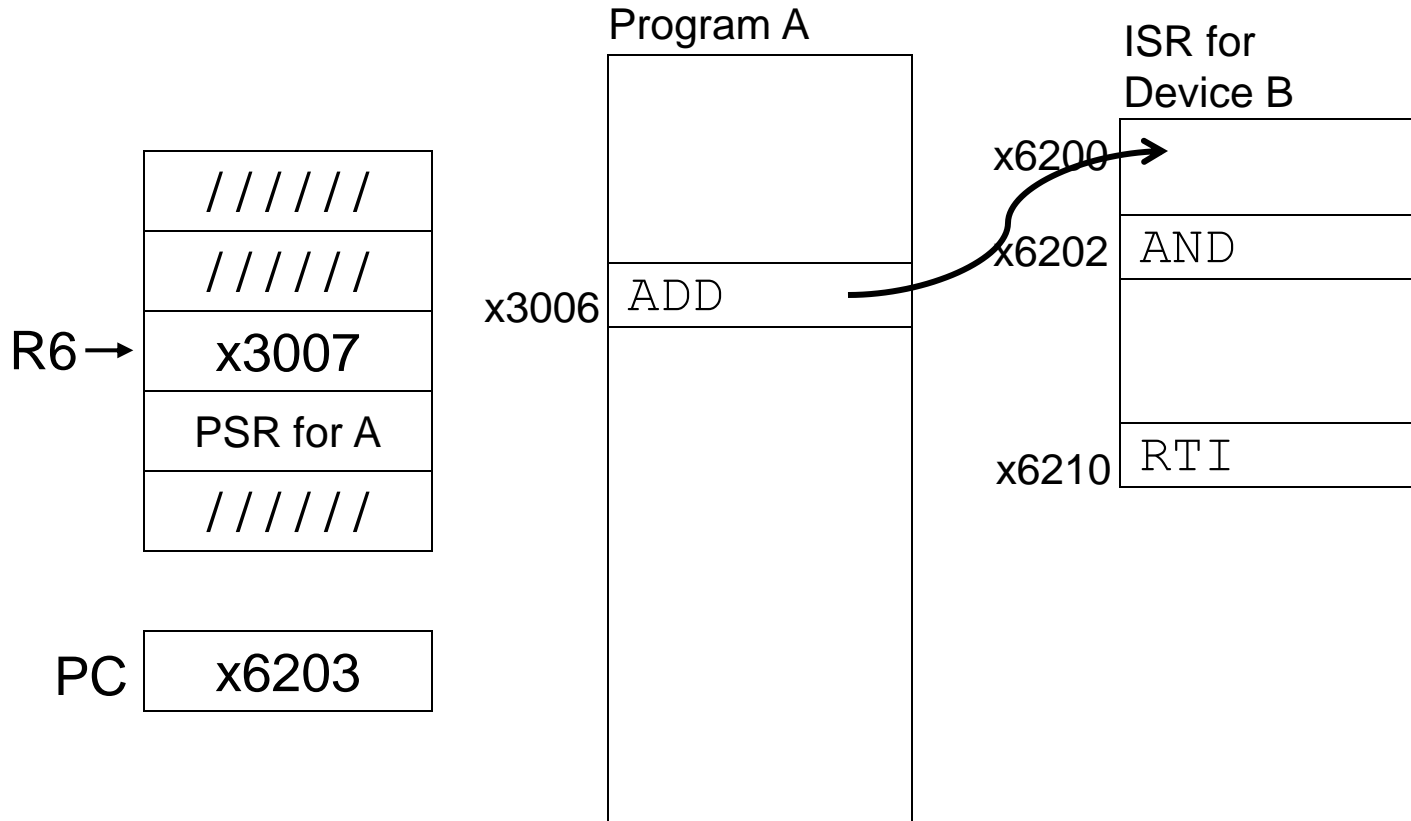


Saved.SSP: S-SSP
Saved.USP: ????

Executing ADD at location x3006 when Device B interrupts.

Example (3)

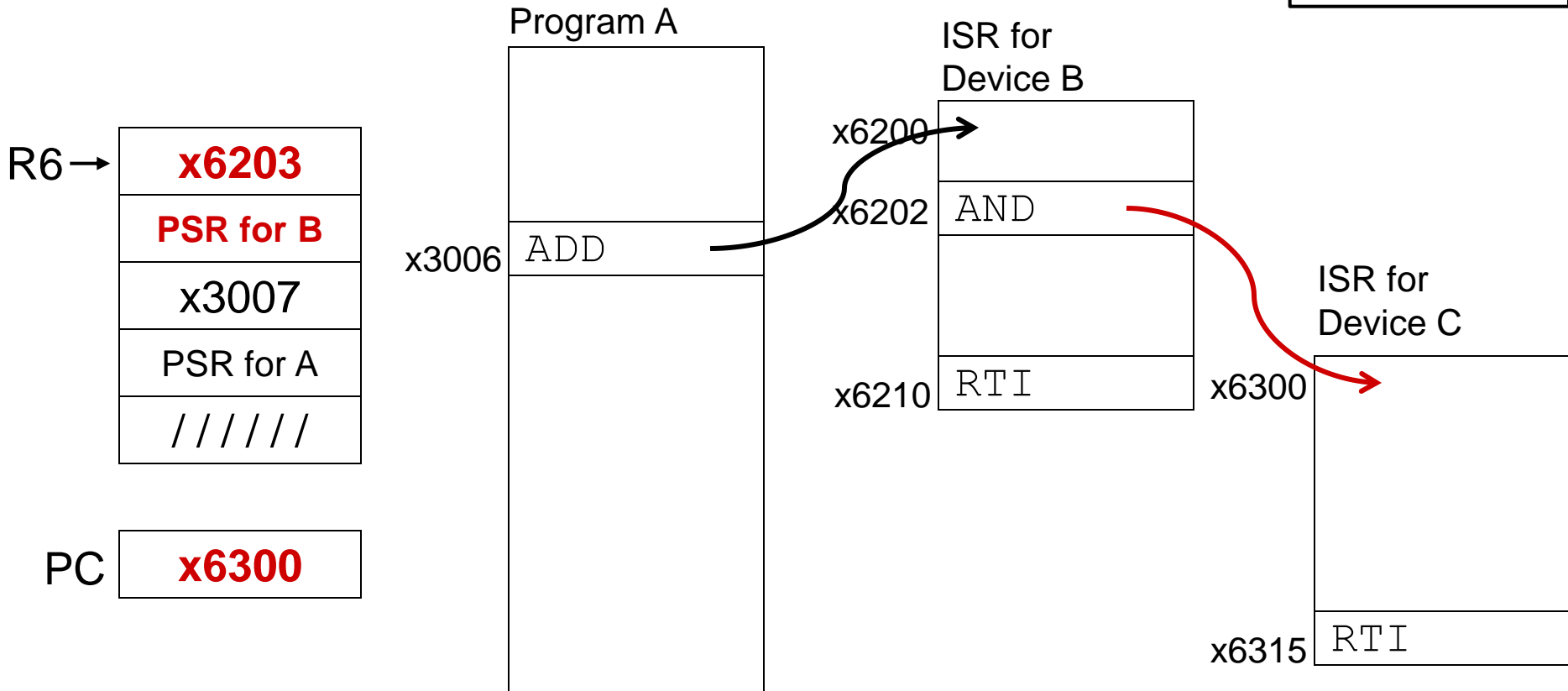
Saved.SSP: S-SSP
Saved.USP: R6-Saved



Executing AND at x6202 when Device C interrupts.

Example (4)

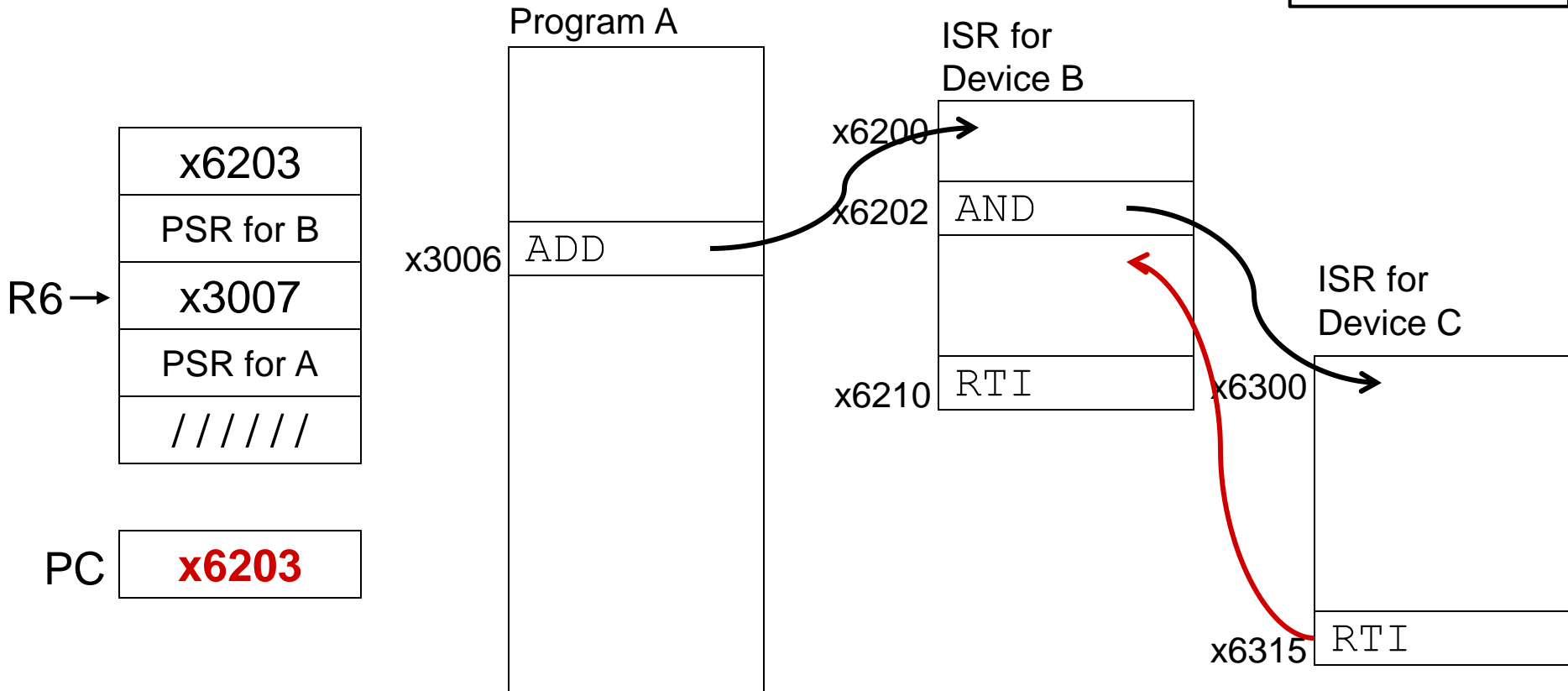
Saved.SSP: S-SSP
Saved.USP: R6-Saved



Push PSR and PC onto stack, then transfer to Device C service routine (at x6300).

Example (5)

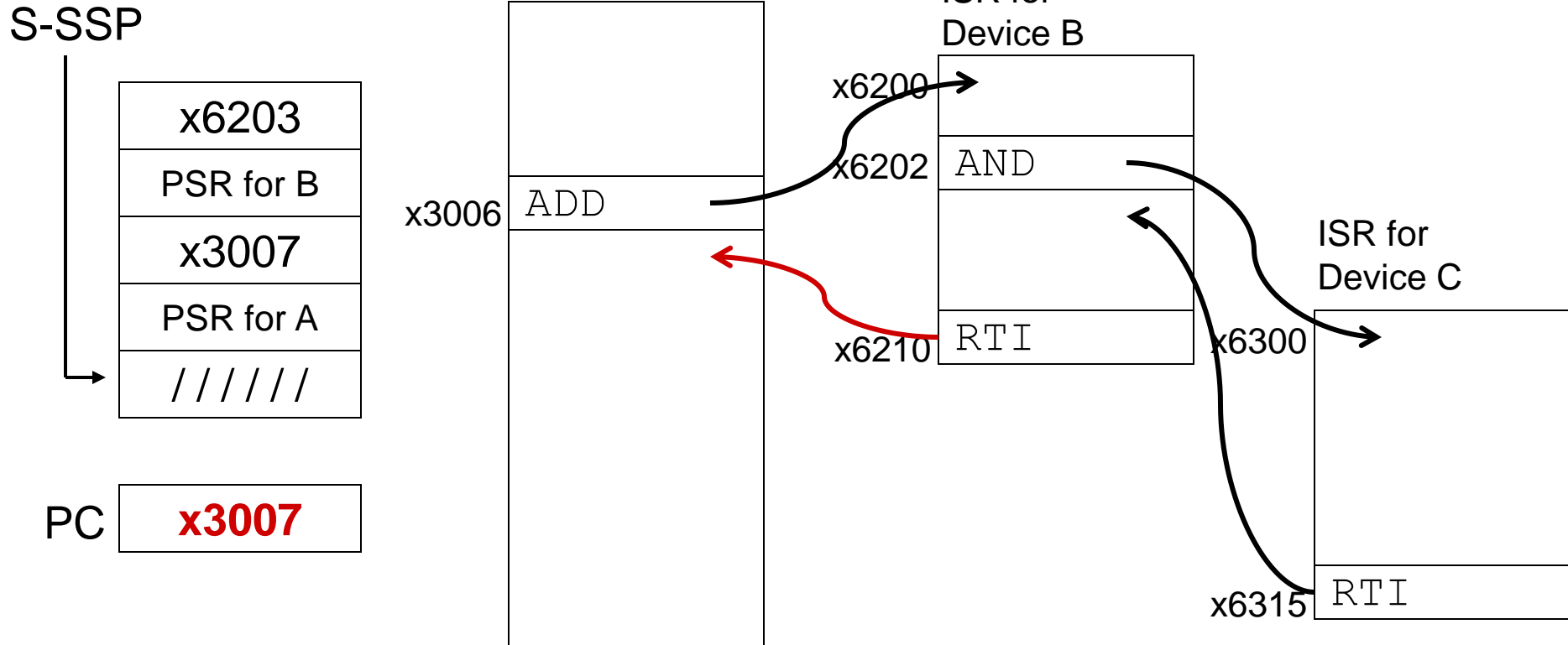
Saved.SSP: S-SSP
Saved.USP: R6-Saved



Execute RTI at x6315; pop PC and PSR from stack.

Example (6)

Saved.SSP: S-SSP
Saved.USP: R6-Saved



Execute RTI at x6210; pop PSR and PC from stack.
Restore R6. Continue Program A as if nothing happened.

Exception: Internal Interrupt

When something unexpected happens inside the processor, it may cause an exception.

Examples:

- Executing an illegal opcode (e.g., 1101)
- Divide by zero
- Accessing an illegal address
- Executing RTI in the User mode

Handled just like an interrupt

- Vector is determined internally by type of exception
- Priority is the same as the program that caused the exception

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- Stack: An Abstract Data Type
 - Push
 - Pop
 - IsEmpty
- Interrupt Service Routine
 - Invoked in response to an interrupt
 - States of the program being interrupted are saved to / restored from the Supervisor Mode Stack
 - We will see the use of the User Mode Stack soon
- Mechanisms to get attention from the operating system (OS)
 - System calls (via TRAP instruction)
 - Interrupts
 - Exceptions (processed in the same way as interrupts)